RESULTS TO BE DISCUSSED

1) MIP CALIBRATION METHOD

2) COMPARISON BETWEEN MIP, Pi0 AND ELASTIC CALIBRATION

3) CLARIFICATION ABOUT THE VTP-FADC

MIP CALIBRATION

- Kinematics x60_3 : SHMS = 35.02 deg HMS=16.48 deg NPS = 18.54 deg

- Configuration: Coin_sparse

- RUNS ANALYZED (**LH2**) : 2011, 2014, 2015, 2016 and 2017



- Took the 8 neighbors to the current block

- T(neighbor block) - T(current block) < 5 ns (to ensure that there is no pulse in the adjacent blocks)

- E(neighbor block) = 0 (1block clusters)

- Applied Exponential decay + Landau fit to determine the peak position.

- Calculated the calibration coefficients by :

- Kinematics x50_4 : SHMS = 31.75 deg HMS=16.91 deg NPS = 15.48 deg

- Configuration: Coin_sparse_low

- RUNS ANALYZED (**LH2**) : 2494, 2550, 2571, 2603, 2632, 2657





COMPARISON BETWEEN MIP, Pi0 AND ELASTIC CALIBRATION (coin_sparse)



COMPARISON BETWEEN MIP, Pi0 AND ELASTIC CALIBRATION (coin_sparse)



==>> Pi0 calibration method is a slightly better in terms of peak position with respect to the MIP and to the elastic calibration.



==>> Same dependency on x (closer to the beam line) is seen between the MIP's and the Pi0 calibration coefficients.



COIN_SPARSE_LOW

LH2

Before MIP and Pi0 Calibration



COIN_SPARSE_LOW



==>> Pi0 calibration method is better in "coin_sparse_low" too.



CLARIFICATION ABOUT THE VTP-FADC

ENERGY

