

KaonLT Meeting

July 31st, 2024

Richard Trotta

Previous functional forms...

$$\sigma_L = p_1 \cdot Q_{F,L} \cdot t_{pole} \cdot e^{-p_6|-t|}$$

$$\sigma_T = p_5(p_6 + e^{-p_7 \cdot |-t|}) \cdot Q_{F,T}^{p_8}$$

$$\sigma_{LT} = \frac{p_9}{1+Q^2} \cdot e^{-p_{10}|-t|} \cdot \sin \theta_K$$

$$\sigma_{TT} = \frac{p_{13}}{(1+Q^2)} \cdot t_{pole} \cdot e^{-p_{14}Q^2} \cdot \sin^2 \theta_K$$

$$Q_{F,L} = \frac{Q^2}{1 + 1.77Q^2 + 0.12(Q^2)^2}$$

$$t_{pole} = \frac{|-t|}{(|-t| + m_K^2)^2}$$

$$Q_{F,T} = \frac{e^{-(Q^2)^2}}{Q^2}$$

Newer functional forms...

$$\sigma_L = p_1 \cdot Q_{F,L} \cdot t_{pole} \cdot e^{-p_6|-t|}$$

$$\sigma_T = (p_5 \cdot e^{-p_6 \cdot |-t|} + p_7 \cdot |-t|) \cdot Q_{F,T}^{p_8}$$

$$\sigma_{LT} = \frac{p_9}{1+Q^2} \cdot e^{-p_{10}|-t|} \cdot \sin \theta_K$$

$$Q_{F,L} = \frac{Q^2}{1 + 1.77Q^2 + 0.12(Q^2)^2}$$

$$t_{pole} = \frac{|-t|}{(|-t| + m_K^2)^2}$$

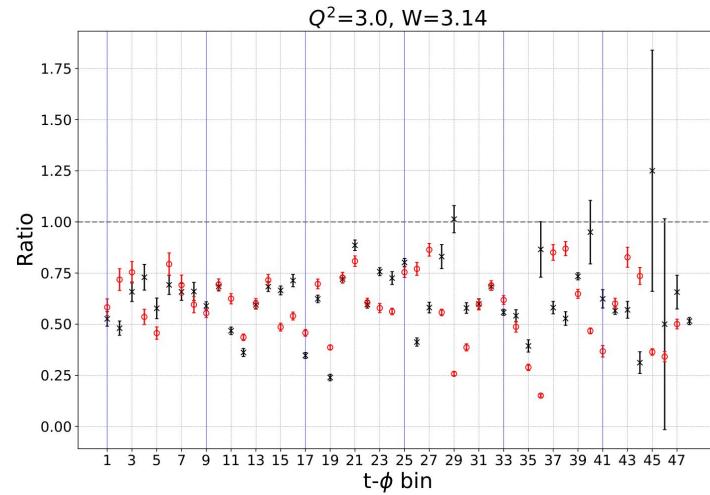
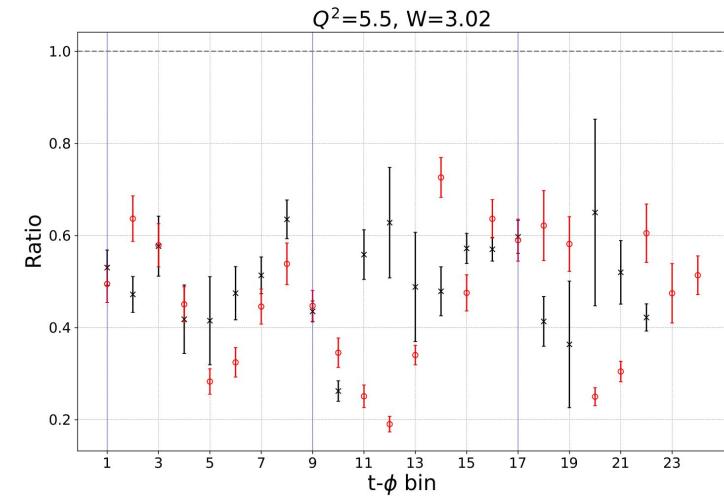
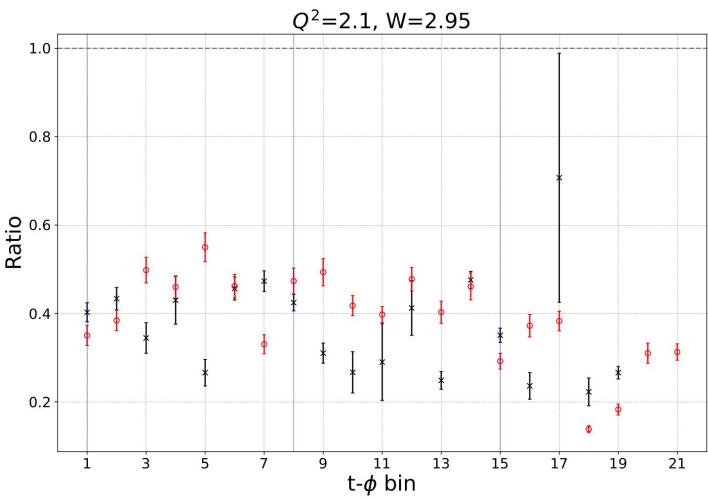
$$Q_{F,T} = \frac{e^{-(Q^2)^2}}{Q^2}$$

$$\sigma_{TT} = \frac{p_{13}}{(1+Q^2)} \cdot t_{pole} \cdot e^{-p_{14}Q^2} \cdot \sin^2 \theta_K$$

$Q^2=2.115, W=2.95$

$Q^2=3.0, W=3.14$

$Q^2=5.5, W=3.02$



****i=1

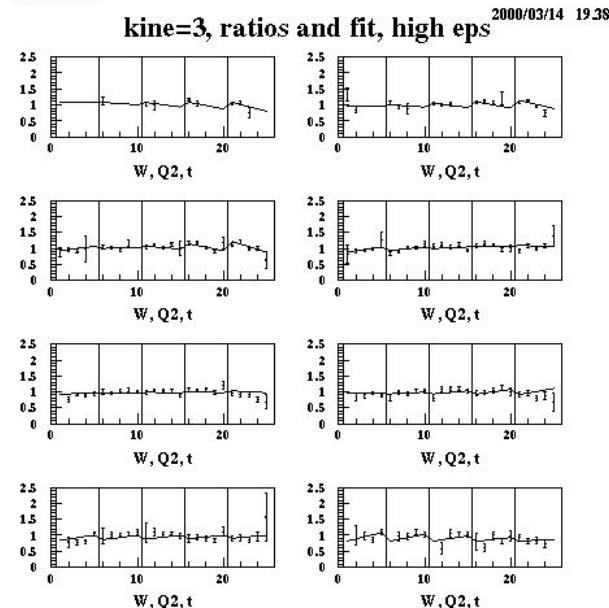
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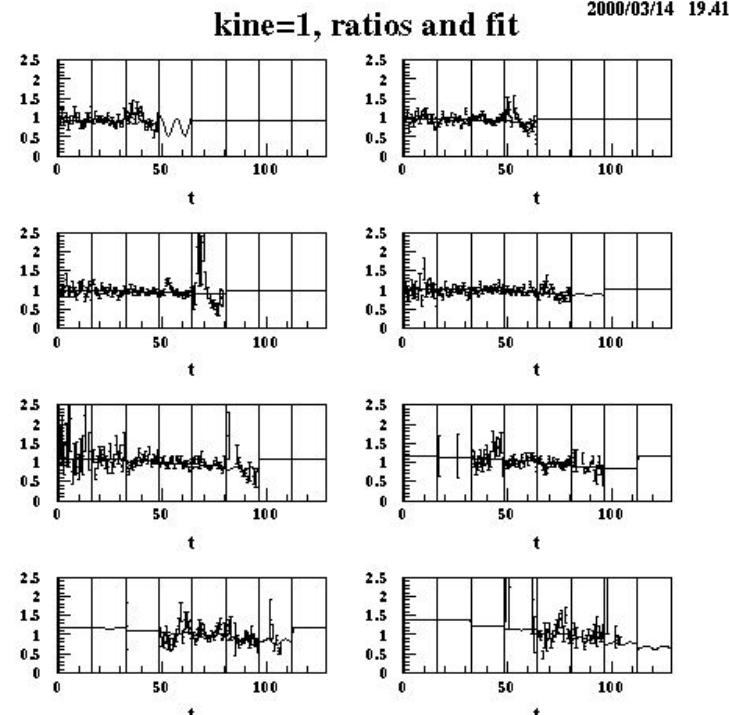
$$a + b \cdot (W - W_c) + c \cdot (Q^2 - Q_c^2) + d \cdot (W - W_c) \cdot (Q^2 - Q_c^2)$$

FIGURE 1



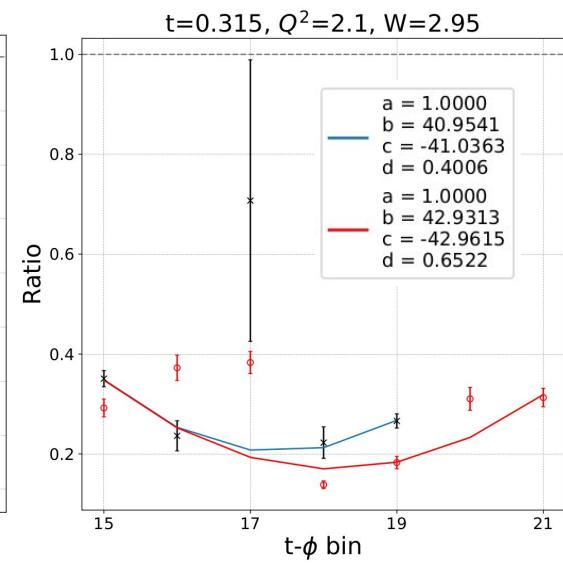
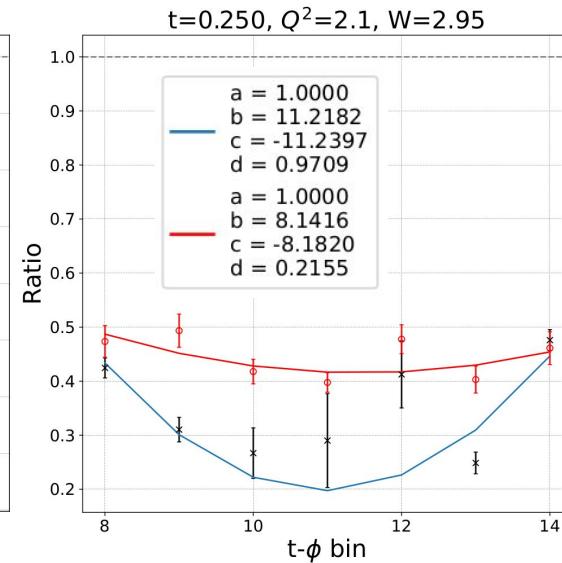
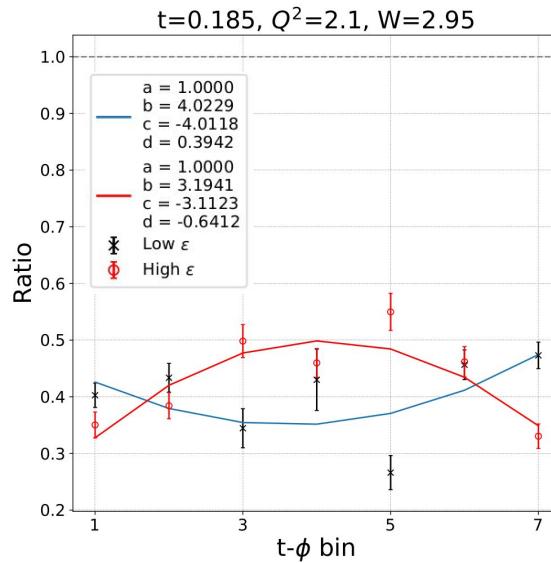
$$a + b \cdot \sin^2 \theta + c \cdot \sin \theta \cos \phi + d \cdot \sin^2 \theta \cos 2\phi$$

FIGURE 1



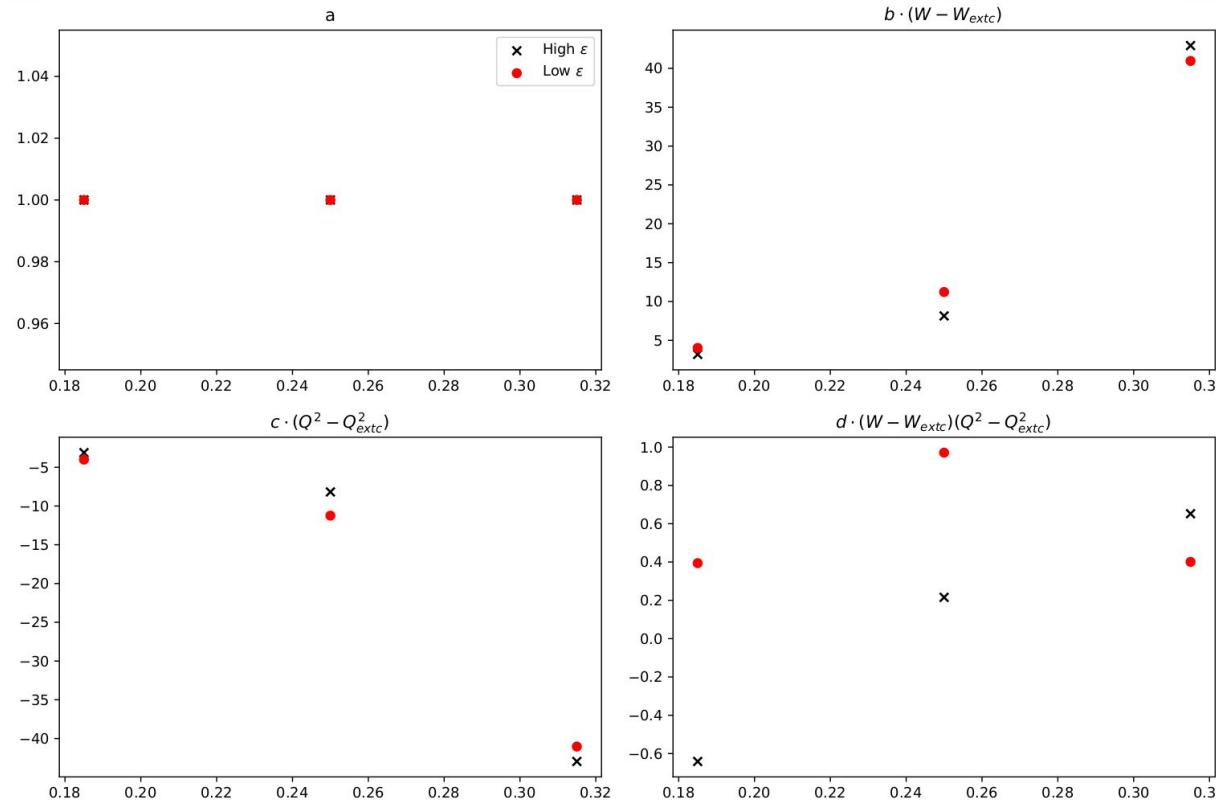
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$Q^2=2.115, W=2.95$



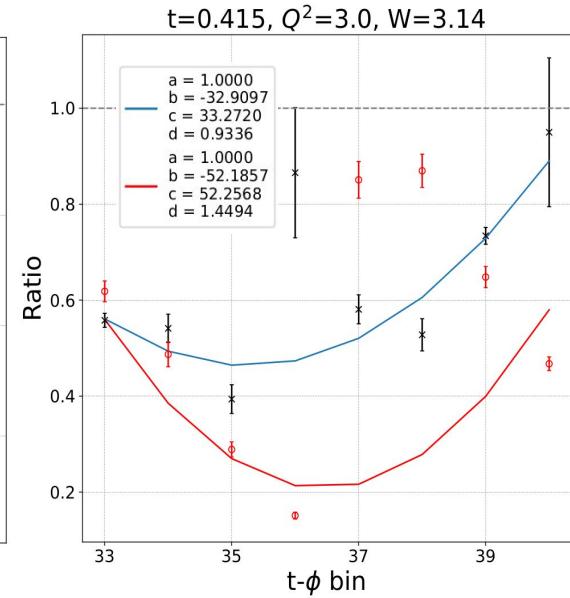
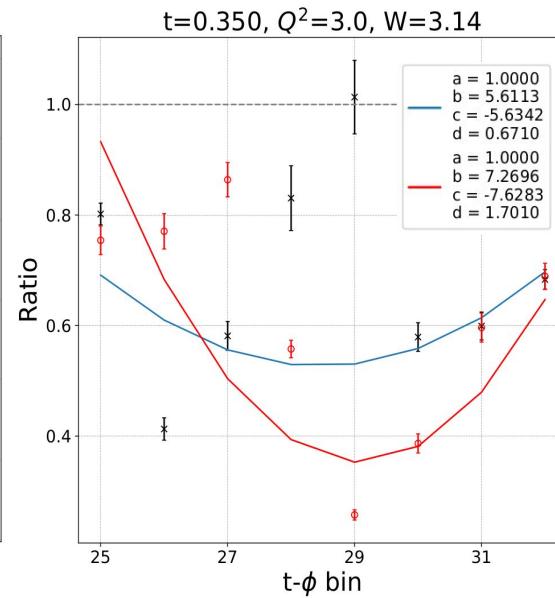
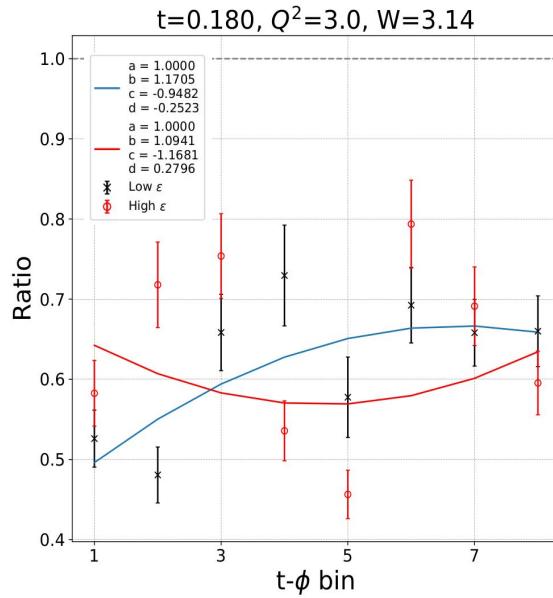
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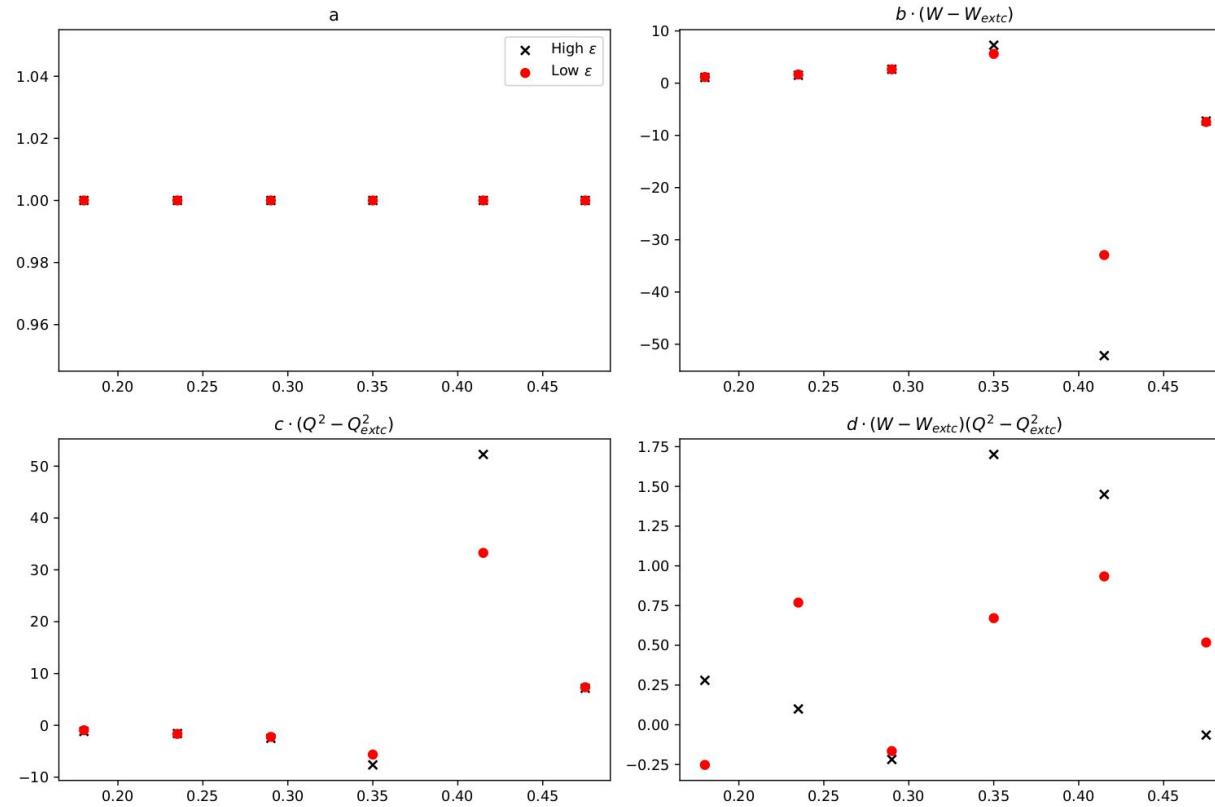
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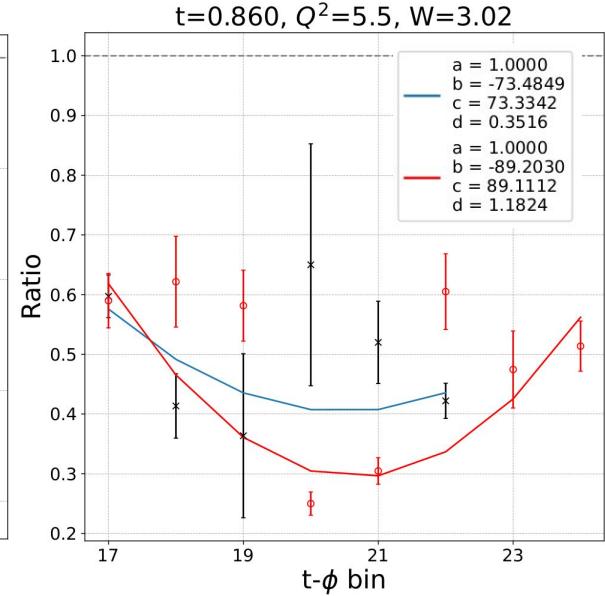
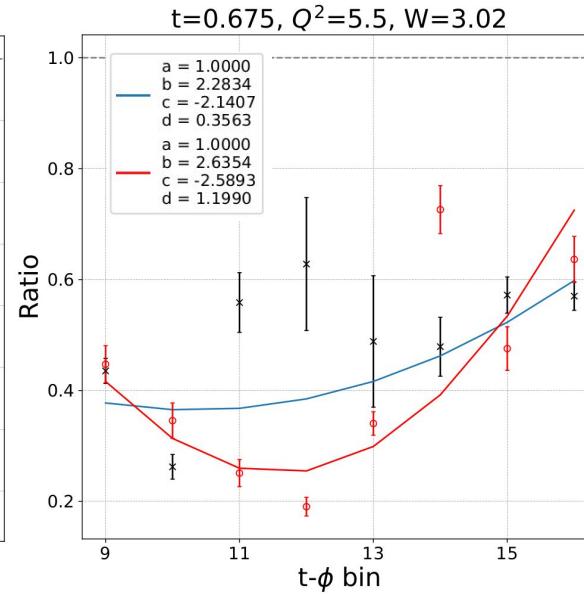
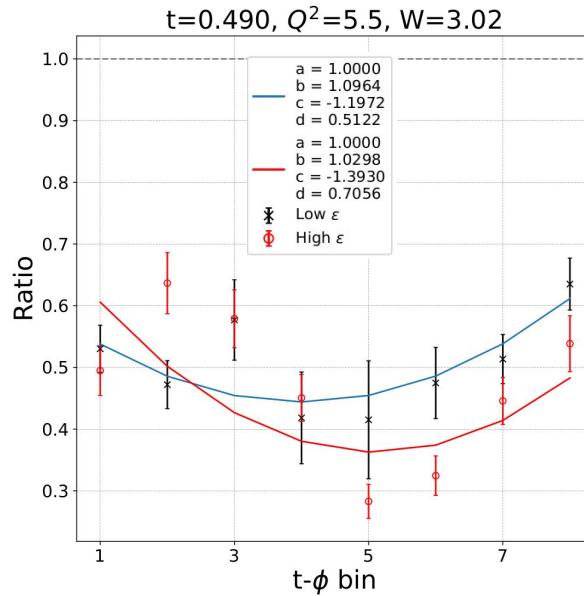
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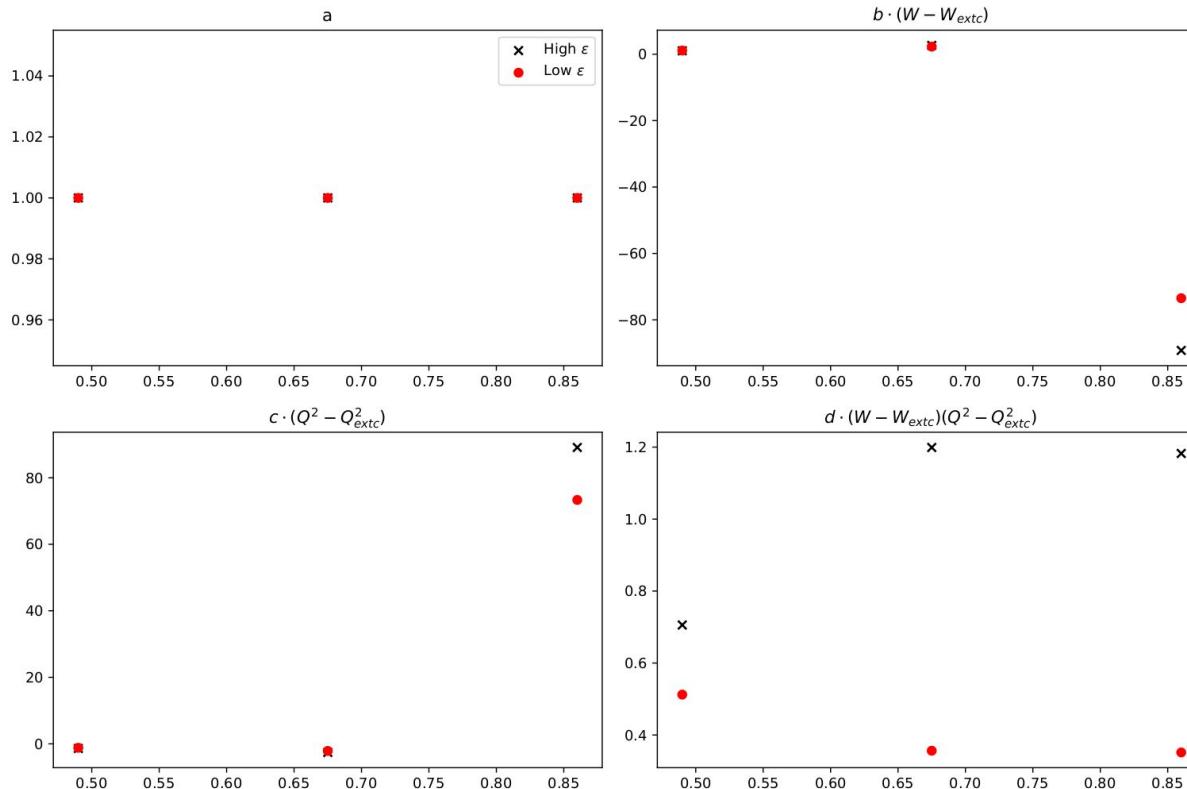
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$Q^2=5.5, W=3.02$



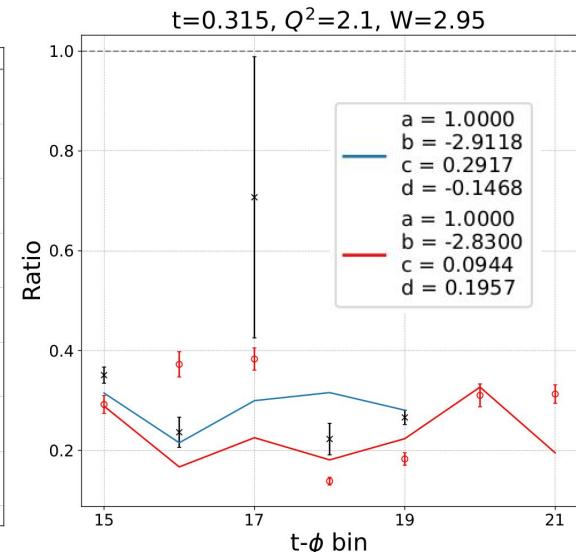
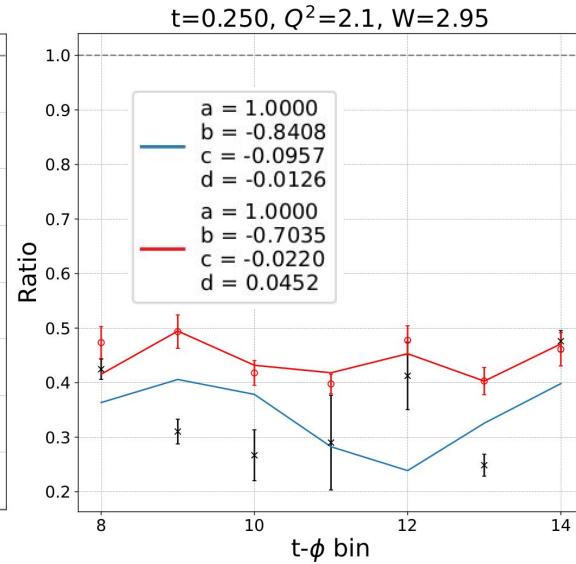
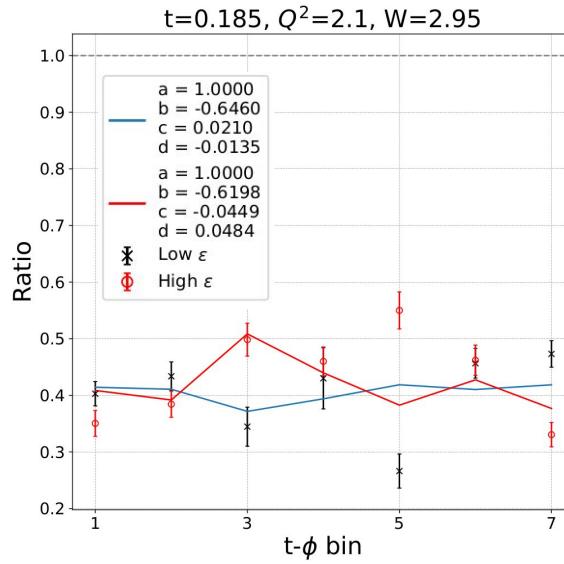
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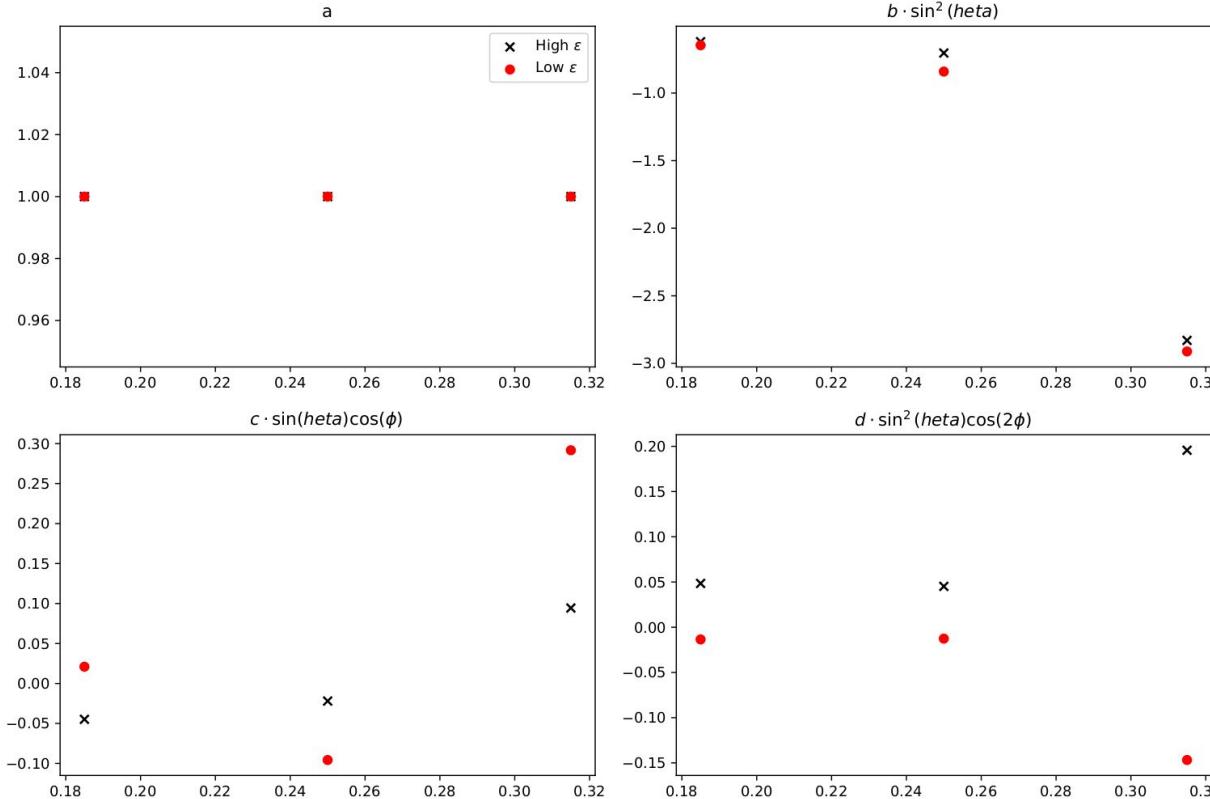
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$$a + b \cdot \sin^2 \theta + c \cdot \sin \theta \cos \phi + d \cdot \sin^2 \theta \cos 2\phi$$

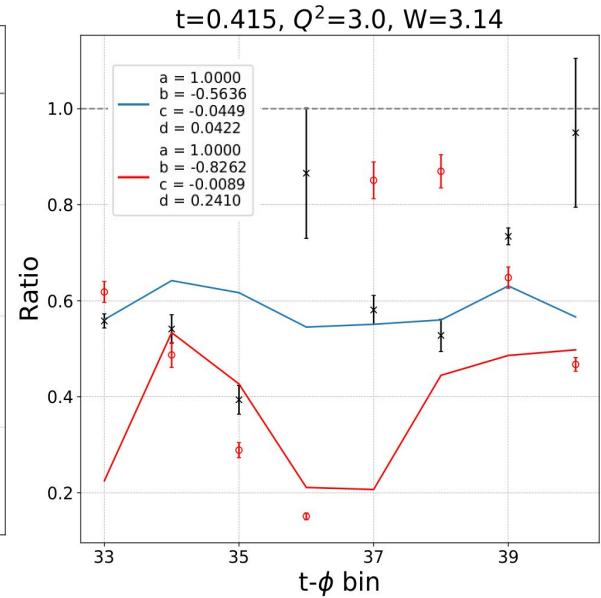
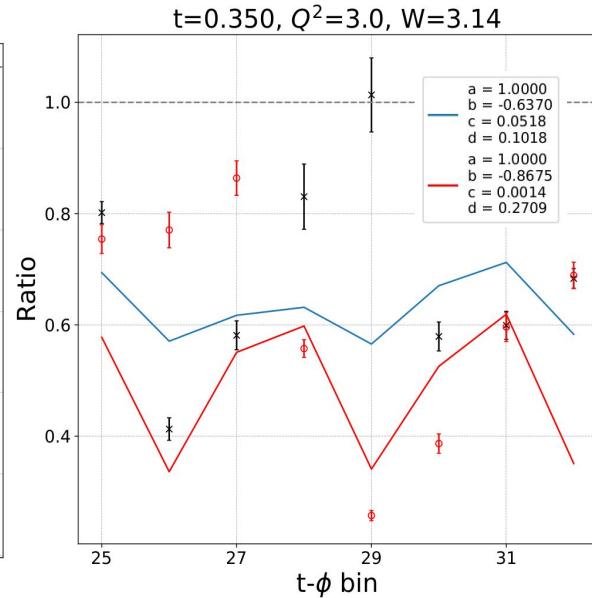
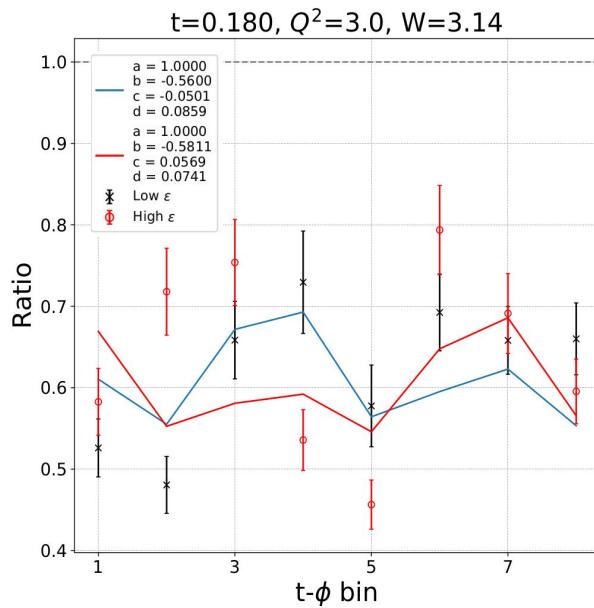
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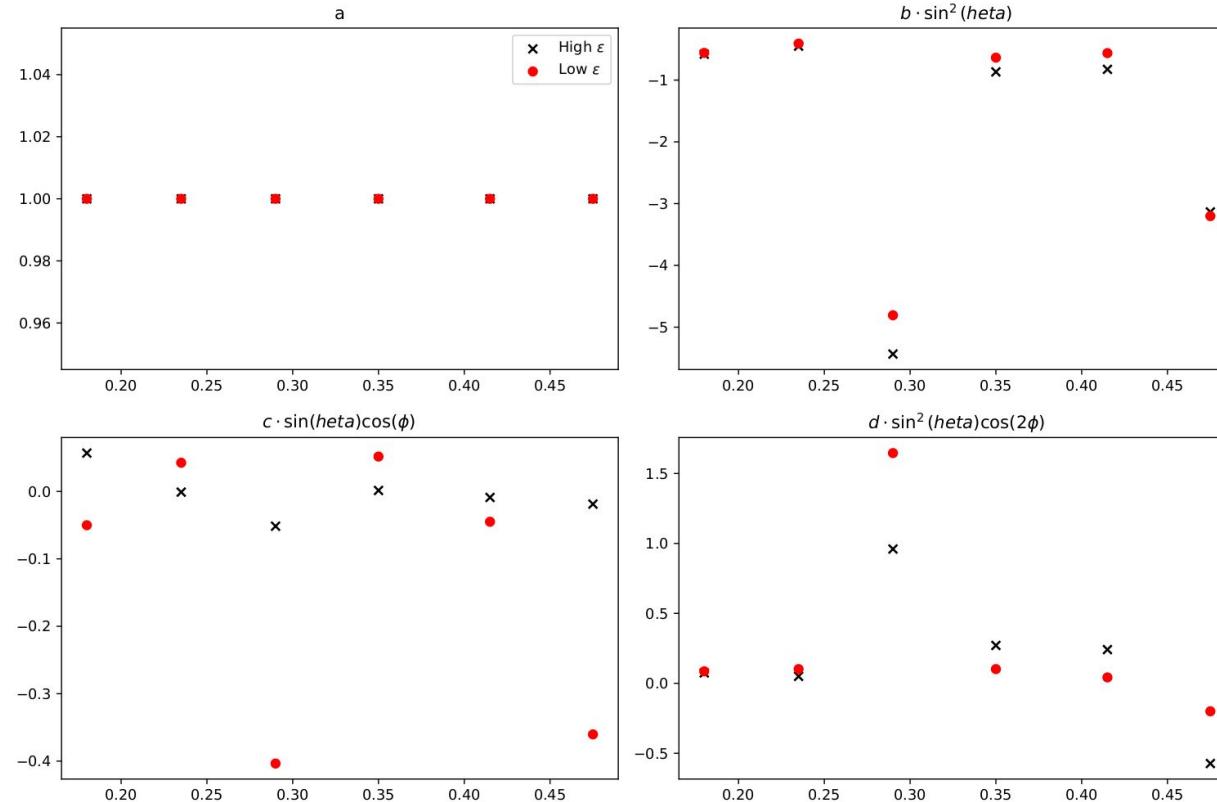
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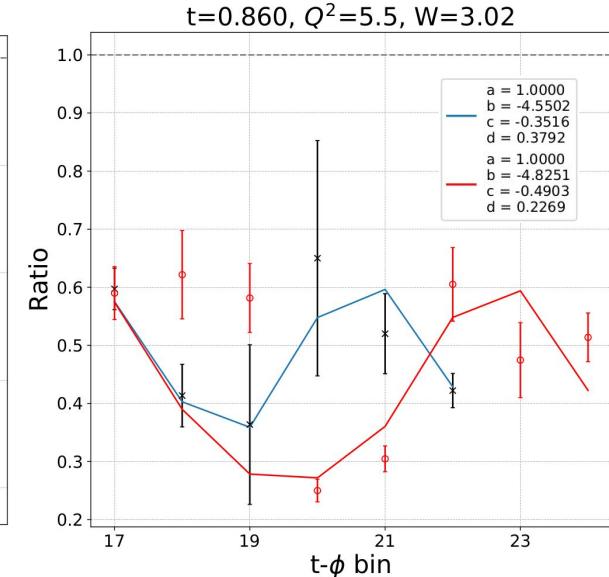
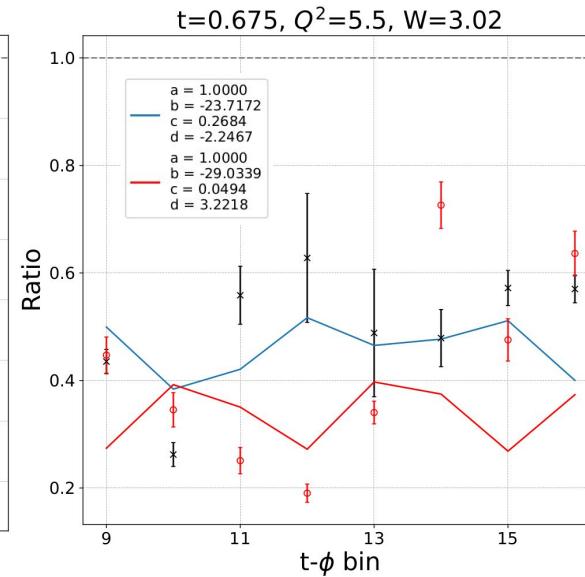
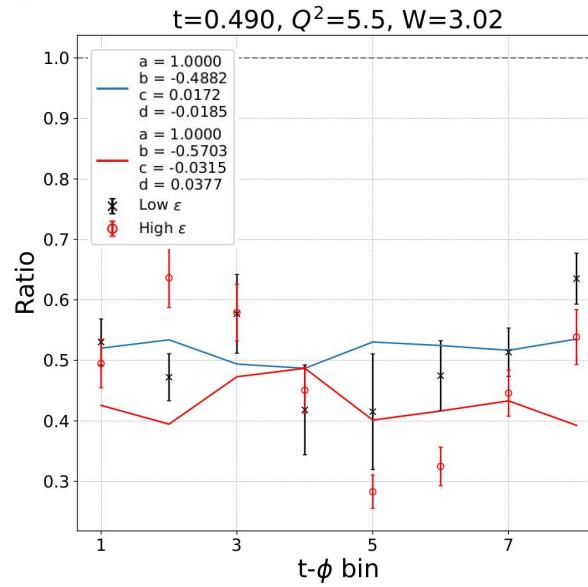
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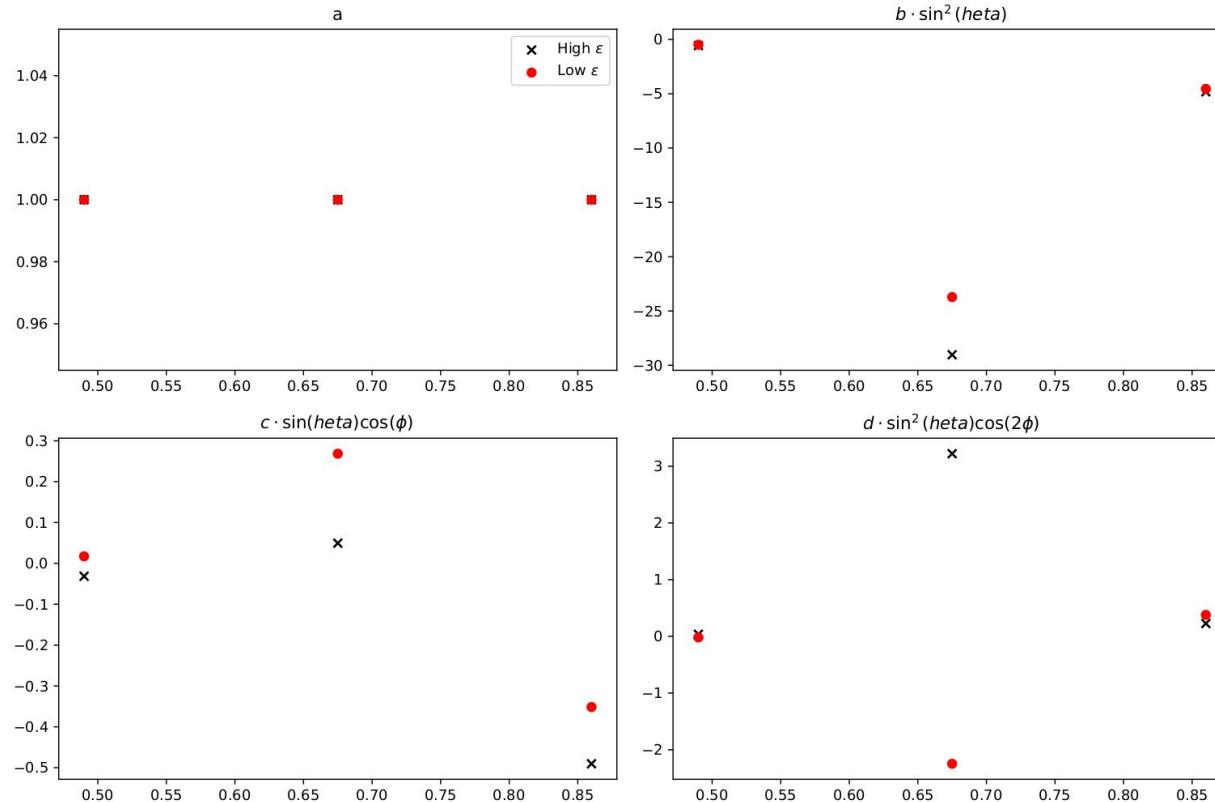
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